HITACHI

Mini-Excavator Z_Axis50U **Specifications**

Rated Engine Power

DIN 6271, net 29.3 kW (39.8 PS) SAE J1349, net 29.9 kW (40.1 hp)

Operating Weight (Rubber shoes) (Grouser shoes) 2-pillar canopy version 4 670 kg 4 810 kg 4-pillar canopy version 4 870 kg 4 730 kg

4 790 kg

4 930 kg

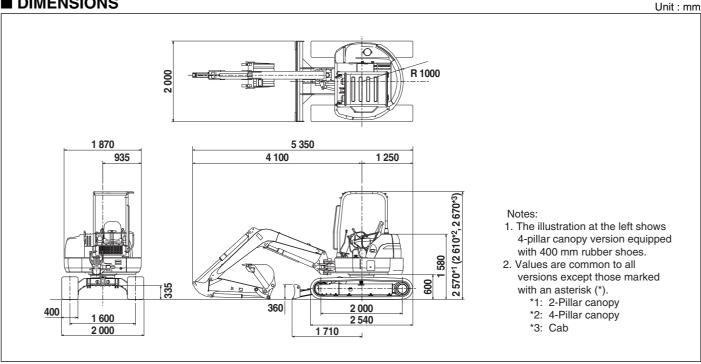
Cab version **Backhoe Buckets**

ISO 7451 0.10 - 0.17 m³

The 2- or 4-pillar canopy, or cab can be mounted on the upperstructure according to job needs and applicable regulations. The 4-pillar canopy and cab conform to TOPS (ISO 12117) and FOPS (ISO 10262, Level 1)* requirements.

* Cab requires optional top guard.

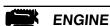




■ WORKING RANGES

Unit: mm 2 100*1 (2 650*2) 800 at 60° swing 5 640*1 (5 150*2) 800 at 80° swing 3 950*1 (3 530*2) 425 Notes: 1. The illustration at the left shows 4-pillar canopy version equipped with 0.16 m³ bucket, 1.34 m arm and 400 mm rubber 2 850 009 shoes. 2. Values are common to all versions except those marked with an asterisk (*). *1: 2-Pillar canopy *2: 4-Pillar canopy and cab 5 800





Model	Isuzu CC-4LE2
Type	Water-cooled, 4-cycle, 4-cylinder
	direct injection type diesel engine
Rated power	29.3 kW (39.8 PS)
DIN 6271, net	at 2 200 min ⁻¹ (rpm)
	29.9 kW (40.1 hp)
SAE J1349, net	at 2 200 min ⁻¹ (rpm)
Maximum torque	145 N·m (14.8 kgf·m)
	at 1 600 min ⁻¹ (rpm)
Piston displacement	2.179 L
Bore and stroke	85 mm x 96 mm
Battery	1 x 12 V, 52 Ah



HYDRAULIC SYSTEM

The HHH system for job efficiency and smooth combined operations.

Main pumps	One variable displacement axial
	piston pumps
Maximum oil flow	110 L/min
Pilot pump	One gear pump
Maximum oil flow	11.0 L/min

Relief Valve Settings

Implement circuit	24.5 MPa (250 kgf/cm ²)
	19.6 MPa (200 kgf/cm ²)
	24.5 MPa (250 kgf/cm ²)
Pilot circuit	3.9 MPa (40 kgf/cm ²)

Hvdraulic Cvlinders

High-strength piston rods and tubes. Cylinder cushion mechanisms provided in boom raise, arm roll-in and roll-out circuits to absorb shocks at stroke ends.

Dimensions

	No.	Bore	Rod dia.	Stroke
Boom	1	95 mm	55 mm	707 mm (696 mm)
Arm	. 1	80 mm	50 mm	738 mm
Bucket	. 1	75 mm	45 mm	551 mm
Boom swing	. 1	80 mm	50 mm	575 mm
Blade	. 1	105 mm	50 mm	140 mm

Note: The figure in () shows the stroke for 4-pillar canopy version and cab version.



CONTROLS

Hydraulic pilot control levers for all operations.



SWING MECHANISM

High-torque, axial piston motor with planetary reduction gear. Swing circle is single-row, shear-type ball bearing with induction-hardened internal gear. Internal gear and pinion are immersed in lubricant. Swing parking brake is springset/hydraulic-released disc type. Swing shockless valve built in swing motor absorbs shocks when stopping swing, ensuring smooth stops.



UNDERCARRIAGE

Tracks

Tractor-type undercarriage. Welded track frame using carefully selected materials. Side frame welded to track frame.

Numbers of Rollers on Each Side

Upper roller1
Lower rollers4

Traction Device

Each track driven by a high-torque, 2-speed axial piston motor through planetary reduction gear, allowing counter-rotation of the tracks. Travel shockless relief valve built in travel motor absorbs shocks when stopping travel, ensuring smooth stops.

Travel speeds (rubber shoes)	High : 0 - 4.4 km/h
	Low : 0 - 2.2 km/h
Travel speeds (grouser shoes)	High : 0 - 4.1 km/h
	Low: 0 - 2.0 km/h
Gradeability	30 degrees (58%) continuous



WEIGHTS AND GROUND PRESSURE

Equipped with 2.80 m boom, 1.34 m arm and 0.16 m³ (PCSA heaped) bucket

	Operating weight	Ground pressure
2-Pillar canopy version	· ·	•
400 mm rubber shoes	. 4 670 kg	26 kPa (0.27 kgf/cm ²)
400 mm grouser shoes.	. 4 810 kg	27 kPa (0.28 kgf/cm ²)
4-Pillar canopy version		
400 mm rubber shoes	. 4 730 kg	27 kPa (0.27 kgf/cm ²)
400 mm grouser shoes.	. 4 870 kg	28 kPa (0.28 kgf/cm ²)
Cab version		
400 mm rubber shoes	. 4 790 kg	27 kPa (0.27 kgf/cm ²)
400 mm grouser shoes.	. 4 930 kg	28 kPa (0.29 kgf/cm ²)



FRONT-END ATTACHMENTS

Backhoe Buckets

ISO	Wic	lth	No. of		Use		
7451 capacity	Without side cutters	With side cutters	teeth	Weight	1.34 m Std. arm	1.69 m Long arm	
0.10 m ³	405 mm	450 mm	3	90 kg	Α	Α	
0.11 m ³	455 mm	500 mm	3	94 kg	Α	Α	
0.13 m^3	505 mm	550 mm	4	103 kg	Α	Α	
0.14 m^3	555 mm	600 mm	4	108 kg	Α	Α	
0.16m^3	605 mm	650 mm	4	114 kg	Α	В	
0.17 m^3	655 mm 700 mm		655 mm 700 mm 4 117 kg		117 kg	В	С
	Arm c	24.5 kN (2 500 kgf)	21.1 kN (2 150 kgf)				
	Bucke	37.3 kN (3 800 kgf)				

A: General digging B: Light-duty digging

C: Loading

Boom swing angle.....Left 60°, Right 80°



Zaxis**5**0U

STANDARD EQUIPMENT

Water-separator for engine fuel system

Hydraulic System

- Hydraulic pilot type control levers
- Pilot control shut-off levers
- Anti-drift valve for front attachments
- Two-speed travel system
- Swing parking brake

Operator's Room

- Two work lights
- Heater*2

Engine

Notes: *1: For 4-pillar canopy and Windshield wiper*2 cab versions

*2: For cab versions

["]

*1.39

1.36

1.32

1.32

- Evacuation hammer*2 Seat belt*1
- Utility box

Undercarriage

- 400 mm rubber shoes
- Semi-long stay blade

Front Attachments

- 2.8 m boom
- 1.34 m arm
- 0.16 m³ hoe bucket
- Bucket clearance adjusting device
- O-ring type pin-seals for hoe bucket
- HN bushing

OPTIONAL EQUIPMENT

Engine

Auto-idling system

Hydraulic System

- Hydraulic P.T.O. port
- Hydraulic piping for breaker
- Travel parking brake
- Swing motion alarm device with lamp
- Travel motion alarm device

Operator's Room

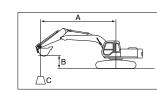
- Heater*2
- Air cooler*3
- Seat belt*1
- Windshield washer*3 Notes: *1 : For 2-pillar canopy version
- Wrist rest *2 : For 2- and 4-pillar canopy
- 12V outlet versions *3: For cab version · Air cleaner inner element
- FOPS top guard*3
- 2-way control lever pattern selector valve (Excavator/Backhoe loader)

Undercarriage

- 400 mm grouser shoes
- 400 mm triangle shoes
- 550 mm grouser shoes
- 400 mm pad crawler shoes
- Long stay blade

Front Attachments

- 1.69 m arm
- Backhoe buckets; see page 2.



A: Load radius B: Load point height C: Lifting capacity

I Init: t

4.81

With dozer blade above ground

Conditions

Rubber shoes: 400 mm

Arm: 1.34 m

ISO 7451

Bucket: 0.16 m³

■ LIFTING CAPACITIES

(Equipped with 2-pillar canopy)

Load Point

Height

3 m

2 m

1 m

Ground

– 1 m

1.19

1.09

1.04

1.04

Rating over-side or 360 degrees Rating over-front

						Ornic.
_	Radius m	5	Maximum Reach			
	Ů		Ů		Ů	meter
0.77	*0.94			*0.47	*0.47	5.25
0.74	0.91	0.50	0.62	0.43	*0.48	5.54
0.70	0.87	0.49	0.60	0.41	*0.51	5.57
0.68	0.84	0.48	0.59	0.44	0.54	5.34

With dozer blade on ground

With dozer blade on ground Unit: t										
		Load Radius 3 m 4 m 5 m					Maximum Reach			
Conditions	Load Point Height		ď		Ъ		ď		Ů	meter
Arm: 1.34 m	3 m			0.77	*0.94			*0.47	*0.47	5.25
	2 m	1.19	*1.39	0.74	*1.10	0.50	*0.85	0.43	*0.48	5.54
Bucket: 0.16 m ³ ISO 7451	1 m	1.09	*2.15	0.70	*1.37	0.49	*1.10	0.41	*0.51	5.57
Rubber shoes: 400 mm	Ground	1.04	*2.41	0.68	*1.55	0.48	*1.16	0.44	*0.58	5.34
	– 1 m	1.04	*2.29	0.67	*1.55			0.52	*0.72	4.81

0.83

0.67

Notes: 1. Rating are based on SAE J1097.

- 2. Lifting capacity of the ZAXIS Series does not exceed 75% of tipping load with the machine on firm, level ground or 87% full hydraulic capacity.
- 3. The load point is a hook (not standard equipment) located on the back of the bucket.

0.52

0.64

4. *Load limited by hydraulic capacity.



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The Specifications include data that are not applicable to certain areas. Optional equipment may vary with territory specifications. Specifications are subject to change without notice.

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