HITACHI

Mini-Excavator Z_Axis35U **Specifications**

Rated Engine Power

DIN 6271, net 22.5 kW (30.6 PS) SAE J1349, net 23.0 kW (30.9 hp)

Operating Weight (Rubber shoes) (Grouser shoes) 2-Pillar canopy version 3 480 kg 3 550 kg 4-Pillar canopy version 3 540 kg 3 610 kg Cab version 3 600 kg 3 670 kg

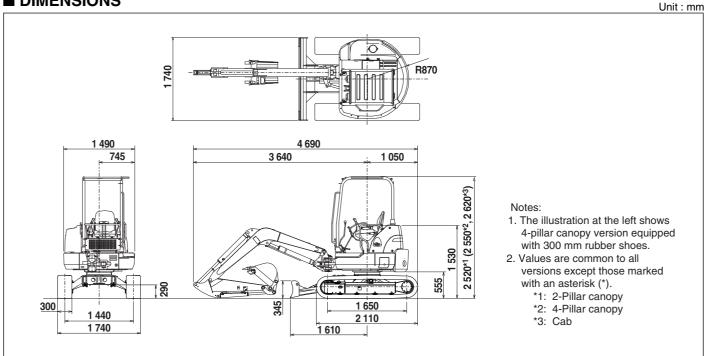
Backhoe Buckets

ISO 7451 0.055 - 0.15 m³

The 2- or 4-pillar canopy, or cab can be mounted on the upperstructure according to job needs and applicable regulations. The 4-pillar canopy and cab conform to TOPS (ISO 12117) and FOPS (ISO 10262, Level 1)* requirements.

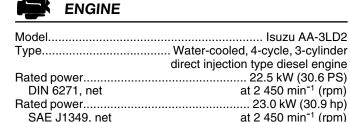
* Cab requires optional top guard.

■ DIMENSIONS



■ WORKING RANGES Unit: mm 1 990*1 (2 160*2) 800*3 at 66° swing 4 850*1 (4 470*2) (725*4 at 51° swing) 680 at 66° swing 3 450*1 (3 100*2) 360 1. The illustration at the left shows 4-pillar 390 canopy version equipped with 0.11 m³ bucket, 1.27 m arm and 300 mm rubber 5 2 1 0 2. Values are common to all versions except 3 150 those marked with an asterisk (*). *1: 2-Pillar canopy *2: 4-Pillar canopy and cab *3: 2- and 4-Pillar canopy *4: Cab







HYDRAULIC SYSTEM

The Optimum Hyraulic System (OHS) uses three pumps for job efficiency and smooth combined operations.

at 1 800 min⁻¹ (rpm)

Main pumps	Two variable displacement axial
	piston pumps
Maximum oil flow	2 x 40.8 L/min
Third pump	One gear pump
Maximum oil flow	
Pilot pump	One gear pump
Maximum oil flow	

Relief Valve Settings

Implement circuit	24.5 MPa (250 kgf/cm ²)
Swing circuit	16.2 MPa (165 kgf/cm ²)
Travel circuit	24.5 MPa (250 kgf/cm ²)
Pilot circuit	3.9 MPa (40 kgf/cm ²)
Pilot circuit	3.9 MPa (40 kgt/cm²)

Hvdraulic Cvlinders

High-strength piston rods and tubes. Cylinder cushion mechanisms provided in boom raise, arm roll-in and roll-out circuits to absorb shocks at stroke ends.

Dimensions

	No.	Bore	Rod dia.	Stroke
Boom	1	80 mm	50 mm	566 mm (540 mm
Arm	. 1	75 mm	40 mm	563 mm
Bucket	. 1	65 mm	40 mm	445 mm
Boom swing	. 1	85 mm	45 mm	517 mm
Blade	. 1	95 mm	45 mm	140 mm

Note: The figure in () shows the stroke for 4-pillar canopy version and cab version.



Hydraulic pilot control levers for all operations.



SWING MECHANISM

High-torque, axial piston motor with planetary reduction gear. Swing circle is single-row, shear-type ball bearing with induction-hardened internal gear. Internal gear and pinion are immersed in lubricant. Swing parking brake is springset/hydraulic-released disc type. Swing shockless valve built in swing motor absorbs shocks when stopping swing, ensuring smooth stops.

Swing speed	9.0 min ⁻¹ (9.0 r	pm)	,
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UNDERCARRIAGE

Tracks

Tractor-type undercarriage. Welded track frame using carefully selected materials. Side frame welded to track frame.

Numbers of Rollers on Each Side

Upper roller1	
Lower rollers4	

Traction Device

Each track driven by a high-torque, 2-speed axial piston motor through planetary reduction gear, allowing counter-rotation of the tracks. Travel shockless relief valve built in travel motor absorbs shocks when stopping travel, ensuring smooth stops. Parking brake is spring-set / hydraulic-released disc type.

Travel speeds (rubber shoes)	High : 0 – 4.4 km/h
,	Low : $0 - 2.8 \text{ km/h}$
Travel speeds (grouser shoes)	High : 0 – 4.3 km/h
	Low : $0 - 2.7 \text{ km/h}$
Gradeability	30 degrees (58%) continuous



WEIGHTS AND GROUND PRESSURE

Equipped with 2.45 m boom, 1.27 m arm and 0.11 m³ (PCSA heaped) bucket

	Operating weight	Ground pressure
2-Pillar canopy version	· ·	•
300 mm rubber shoes	3 480 kg	31 kPa (0.32 kgf/cm ²)
300 mm grouser shoes		32 kPa (0.33 kgf/cm ²)
4-Pillar cab version	_	
300 mm rubber shoes	3 540 kg	32 kPa (0.33 kgf/cm ²)
300 mm grouser shoes	3 610 kg	33 kPa (0.33 kgf/cm ²)
Cab version		
300 mm rubber shoes	3 600 kg	33 kPa (0.33 kgf/cm ²)
300 mm grouser shoes	3 670 kg	33 kPa (0.34 kgf/cm ²)



FRONT-END ATTACHMENTS

Backhoe Buckets

ISO	Wic	dth	No. of		Use			
7451 capacity	Without side cutters	With side cutters	teeth	Weight	1.27 m Std. arm	1.6 7 m Long arm		
0.055 m ³	300 mm	350 mm	3	61 kg	Α	Α		
0.065 m ³	350 mm	400 mm	3	64 kg	Α	Α		
0.08 m ³	400 mm	450 mm	3	67 kg	Α	Α		
0.09 m ³	450 mm	500 mm	4	71 kg	Α	Α		
0.10 m ³	500 mm	550 mm	4	74 kg	Α	Α		
0.11 m ³	550 mm	600 mm	4	78 kg	Α	В		
0.13 m ³	600 mm	650 mm	4	82 kg	В	С		
0.14 m^3	650 mm	700 mm	4	85 kg	С	D		
0.15 m ³	700 mm	750 mm	4	88 kg	С	D		
	Arm c	19.1 kN (1 950 kgf)	16.7 kN (1 700 kgf)					
	Bucke		27.4 kN (2 800 kgf)				

Α:	General digging
R٠	Light-duty diaging

C: Loading

Boom swing angle

2- and 4-pillar canopy versions	Left 66°, Right 66°
Cab version	Left 66°, Right 51°



STANDARD EQUIPMENT

Engine

Water-separator for engine fuel system

Hydraulic System

- Hydraulic pilot type control levers
- Pilot control shut-off levers
- · Anti-drift valve for front attachments
- Two-speed travel system
- Swing parking brake

Operator's Room

- Two work lights
- Heater*2
- Notes: *1: For 4-pillar canopy and • Windshield wiper*2 • Evacuation hammer*2 cab versions
- Seat belt*1 *2: For cab versions

Undercarriage

- 300 mm rubber shoes
- Semi-long stay blade

Front Attachments

- 2.45 m boom
- 1.27 m arm
- 0.11 m3 hoe bucket
- Bucket clearance adjusting device
- O-ring type pin-seals for hoe bucket
- HN bushing

OPTIONAL EQUIPMENT

Engine

Auto-idling system

Hydraulic System

- Hydraulic P.T.O. port
- · Hydraulic piping for breaker
- Travel parking brake
- Swing motion alarm device with lamp
- Travel motion alarm device

Operator's Room

- Heater*2
- Air cooler*3
- Seat belt*1
- Windshield washer*3 Notes: *1 : For 2-pillar canopy version
- $^{\star 2}$: For 2- and 4-pillar canopy Wrist rest
- 12V outlet versions *3: For cab version • Air cleaner inner element
- FOPS top guard*3
- 2-way control lever pattern selector valve (Excavator/Backhoe loader)

Undercarriage

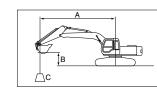
- 300 mm grouser shoes
- 400 mm triangle shoes
- 400 mm grouser shoes
- 300 mm pad crawler shoes

Front Attachments

- 1.67 m arm
- Backhoe buckets; see page 2.

Counterweight

· Weight-added counterweight (260 kg added)



A: Load radius B: Load point height C: Lifting capacity

Linit: +

With dozer blade above ground

■ LIFTING CAPACITIES

(Equipped with 2-pillar canopy)

Rating over-side or 360 degrees 📋 Rating over-front

Trial dozof blade above greatia									Ornic. t	
		Load Radius 2 m 3 m 4 m					Maximum Reach			
Conditions	Load Point Height		Ü		ď		Ů		Ů	meter
Arm: 1.27 m	3 m							0.40	*0.40	4.55
	2 m			*0.71	*0.71	0.48	0.50	0.34	0.34	4.93
Bucket: 0.11 m ³ ISO 7451	1 m			0.72	0.75	0.46	0.48	0.32	0.33	5.01
Rubber shoes: 300 mm	Ground			0.69	0.71	0.45	0.46	0.34	0.35	4.81
	– 1 m	1.33	1.42	0.68	0.71	0.44	0.45	0.41	0.42	4.25

With dozer blade on ground

with dozer blade on ground												
			Load Radius							Maximum Reach		
.	Load Point	2	m	3 m		4 m		Maximum ricacii				
Conditions	Height						Ū		Ū	meter		
Arm: 1.27 m Bucket: 0.11 m ³ ISO 7451 Rubber shoes: 300 mm	3 m							0.40	*0.40	4.55		
	2 m			*0.71	*0.71	0.48	*0.64	0.34	*0.40	4.93		
	1 m			0.72	*1.10	0.46	*0.76	0.32	*0.43	5.01		
	Ground			0.69	*1.34	0.45	*0.87	0.34	*0.50	4.81		
	– 1 m	1.33	*1.94	0.68	*1.30	0.44	*0.85	0.41	*0.65	4.25		

- Notes: 1. Rating are based on SAE J1097.
 - 2. Lifting capacity of the ZAXIS Series does not exceed 75% of tipping load with the machine on firm, level ground or 87% full hydraulic capacity.
- 3. The load point is a hook (not standard equipment) located on the back of the bucket.
- 4. *Load limited by hydraulic capacity



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The Specifications include data that are not applicable to certain areas. Optional equipment may vary with territory specifications. Specifications are subject to change without notice.

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