# **HITACHI**

# Mini-Excavator ZAXISBOU Specifications

Rated Engine Power

DIN 6271, net 22.5 kW (30.6 PS) SAE J1349, net 23.0 kW (30.9 hp)

Operating Weight (Rubber shoes) (Grouser shoes)
2-Pillar canopy version 3 060 kg 3 140 kg
4-Pillar canopy version 3 120 kg 3 200 kg
Cab version 3 180 kg 3 260 kg

**Backhoe Buckets** 

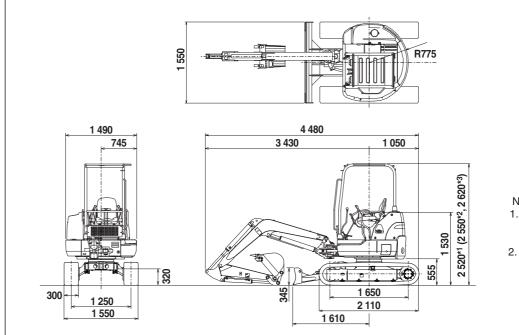
ISO 7451 0.055 - 0.13 m<sup>3</sup>

The 2- or 4-pillar canopy, or cab can be mounted on the upperstructure according to job needs and applicable regulations. The 4-pillar canopy and cab conform to TOPS (ISO 12117) and FOPS (ISO 10262, Level 1)\* requirements.

\* Cab requires optional top guard.

### **■ DIMENSIONS**

Unit: mm

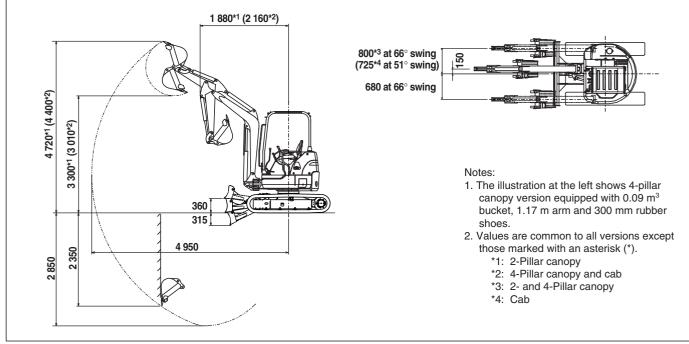


### Notes:

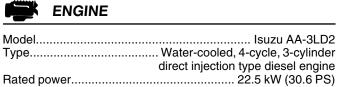
- The illustration at the left shows 4-pillar canopy version equipped with 300 mm rubber shoes.
- Values are common to all versions except those marked with an asterisk (\*).
  - \*1: 2-Pillar canopy
  - \*2: 4-Pillar canopy
  - \*3: Cab

### **■ WORKING RANGES**

Unit : mm







DIN 6271, net	at 2 450 min <sup>-1</sup> (rpm)
Rated power	23.0 kW (30.9 hp)
SAE J1349, net	at 2 450 min <sup>-1</sup> (rpm)
Maximum torque	97 N·m (9.9 kgf·m)
·	at 1 800 min <sup>-1</sup> (rpm)
Piston displacement	1.496 L
Bore and stroke	

......1 x 12 V, 52 Ah



## **HYDRAULIC SYSTEM**

The Optimum Hyraulic System (OHS) uses three pumps for job efficiency and smooth combined operations.

Main pumps	Two variable displacement axial
	piston pumps
Maximum oil flow	2 x 40.8 L/min
Third pump	One gear pump
Maximum oil flow	
Pilot pump	One gear pump
Maximum oil flow	9.9 L/min

### **Relief Valve Settings**

Implement circuit	24.5 MPa (250 kgf/cm <sup>2</sup> )
Swing circuit	13.7 MPa (140 kgf/cm²)
Travel circuit	24.5 MPa (250 kgf/cm <sup>2</sup> )
Pilot circuit	3.9 MPa (40 kgf/cm <sup>2</sup> )

### **Hydraulic Cylinders**

High-strength piston rods and tubes. Cylinder cushion mechanisms provided in boom raise, arm roll-in and roll-out circuits to absorb shocks at stroke ends.

### **Dimensions**

	No.	Bore	Rod dia.	Stroke
Boom	1	75 mm	45 mm	569 mm (541 mm)
Arm	. 1	75 mm	45 mm	589 mm
Bucket	. 1	65 mm	40 mm	440 mm
Boom swing	. 1	85 mm	45 mm	517 mm
Blade	. 1	85 mm	45 mm	135 mm

Note: The figure in ( ) shows the stroke for 4-pillar canopy version and cab version.



### **CONTROLS**

Hydraulic pilot control levers for all operations.



### **SWING MECHANISM**

High-torque, axial piston motor with planetary reduction gear. Swing circle is single-row, shear-type ball bearing with induction-hardened internal gear. Internal gear and pinion are immersed in lubricant. Swing parking brake is springset/hydraulic-released disc type. Swing shockless valve built in swing motor absorbs shocks when stopping swing, ensuring smooth stops.

Swing speed...... 9.0 min<sup>-1</sup> (9.0 rpm)

### **UNDERCARRIAGE**

### **Tracks**

Tractor-type undercarriage. Welded track frame using carefully selected materials. Side frame welded to track frame.

### **Numbers of Rollers on Each Side**

Upper roller1	
Lower rollers4	-

### **Traction Device**

Each track driven by a high-torque, 2-speed axial piston motor through planetary reduction gear, allowing counter-rotation of the tracks. Travel shockless relief valve built in travel motor absorbs shocks when stopping travel, ensuring smooth stops. Parking brake is spring-set / hydraulic-released disc type.

Travel speeds (rubber shoes)	High : 0 – 4.4 km/h
Travel speeds (grouser shoes)	Low : $0 - 2.8 \text{ km/h}$
rraver speeds (grouser snoes)	Low: 0 – 4.3 km/h
Gradeability	30 degrees (58%) continuous



### **WEIGHTS AND GROUND PRESSURE**

Equipped with 2.28 m boom, 1.17 m arm and 0.09 m<sup>3</sup> (PCSA heaped) bucket

	Operating	Ground
	weight	pressure
2-Pillar canopy version		
300 mm rubber shoes	3 060 kg	28 kPa (0.28 kgf/cm <sup>2</sup> )
300 mm grouser shoes	3 140 kg	28 kPa (0.29 kgf/cm <sup>2</sup> )
4-Pillar cab version		
300 mm rubber shoes	3 120 kg	28 kPa (0.29 kgf/cm <sup>2</sup> )
300 mm grouser shoes	3 200 kg	29 kPa (0.29 kgf/cm <sup>2</sup> )
Cab version		
300 mm rubber shoes	3 180 kg	29 kPa (0.29 kgf/cm <sup>2</sup> )
300 mm grouser shoes	3 260 kg	29 kPa (0.30 kgf/cm <sup>2</sup> )



# FRONT-END ATTACHMENTS

### Backhoe Buckets

ISO	Wic	dth	No. of		Use		
7451 capacity	Without side cutters	With side cutters	teeth	Weight	1.17 m Std. arm	1.47 m Long arm	
0.055 m <sup>3</sup>	300 mm	350 mm	3	61 kg	Α	Α	
0.065 m <sup>3</sup>	350 mm	400 mm	3	64 kg	Α	Α	
0.08 m <sup>3</sup>	400 mm	450 mm	3	67 kg	Α	Α	
0.09 m <sup>3</sup>	450 mm	500 mm	4	71 kg	Α	В	
0.10 m <sup>3</sup>	500 mm	550 mm	4	74 kg	В	С	
0.11 m <sup>3</sup>	550 mm	600 mm	4	78 kg	С	С	
0.13 m <sup>3</sup>	600 mm	650 mm	4	82 kg	С	D	
	Arm c		16.7 kN (1 700 kgf)	14.7 kN (1 500 kgf)			
	Bucke	t digging fo	orce		27.5 kN (	2 800 kgf)	

- A: General digging
- B: Light-duty digging
- C: Loading
- D: Not recommended

### Boom swing angle

2- and 4-pillar canopy v	ersionsLeft 66°, Right 66°
Cab version	Left 66°, Right 51°



### **OPTIONAL EQUIPMENT**

Zaxis30U

### **Engine**

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Auto-idling system

### **Hydraulic System**

- Hydraulic P.T.O. port
- Hydraulic piping for breaker
- Travel parking brake
- Swing motion alarm device with lamp
- Travel motion alarm device

### **Operator's Room**

- Heater\*2
- Air cooler\*3
- Seat belt\*1
- Windshield washer\*3 Notes: \*1 : For 2-pillar canopy version
- \*2 : For 2- and 4-pillar canopy Wrist rest
- 12V outlet versions
- $^{\star 3}$ : For cab version • Air cleaner inner element
- FOPS top guard\*3
- 2-way control lever pattern selector valve (Excavator/Backhoe loader)

### Undercarriage

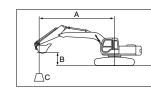
- 300 mm grouser shoes
- 400 mm triangle shoes
- 400 mm grouser shoes
- 300 mm pad crawler shoes

### **Front Attachments**

- 1.47 m arm
- Backhoe buckets; see page 2.

### Counterweight

• Weight-added counterweight (270 kg added)



A: I oad radius B: Load point height

C: Lifting capacity

### With dozer blade above ground

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**Engine** 

swing

and blade

**Hydraulic System** 

STANDARD EQUIPMENT

• Hydraulic pilot type control levers for boom, arm, bucket and

Mechanical linkage type control levers for travel, boom swing

• Pilot control shut-off levers for boom, arm, bucket and swing

Notes: \*1: For 4-pillar canopy and

cab versions

\*2 : For cab versions

Water-separator for engine fuel system

Anti-drift valve for front attachments

Two-speed travel system

Swing parking brake

**Operator's Room** 

Windshield wiper\*2

• Evacuation hammer\*2

• 300 mm rubber shoes

• Semi-long stay blade

**Front Attachments** 

• 0.09 m³ hoe bucket

• Bucket clearance adjusting device

O-ring type pin-seals for hoe bucket

**■ LIFTING CAPACITIES** 

(Equipped with 2-pillar canopy)

Two work lights

Undercarriage

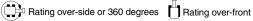
• 2.28 m boom

• 1.17 m arm

HN bushing

• Heater\*2

• Seat belt\*1





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Unit: t

		Load Hadius						Maximum Reach		
<b>_</b>	Load Point Height	2 m		3 m		4 m		Maximum ricacii		
Conditions			Ů		Ū		Ů		Ū	meter
Arm: 1.17 m Bucket: 0.09 m³ ISO 7451 Rubber shoes: 300 mm	3 m			0.55	*0.57			0.30	0.38	4.24
	2 m			0.53	0.68	0.32	0.41	0.24	0.31	4.66
	1 m			0.49	0.63	0.31	0.40	0.23	0.30	4.75
	Ground			0.46	0.60	0.30	0.39	0.25	0.32	4.53
	– 1 m	0.89	1.20	0.46	0.60			0.31	0.40	3.91

### With dozer blade on ground

With dozer blade on ground Unit: t										
			Load Radius 2 m 3 m 4 m					Maximum Reach		
Conditions	Load Point Height		Ů		m U		Ů		Ğ	meter
Arm: 1.17 m Bucket: 0.09 m³ ISO 7451 Rubber shoes: 300 mm	3 m			0.55	*0.57			0.30	*0.58	4.24
	2 m			0.53	*0.70	0.32	*0.64	0.24	*0.57	4.66
	1 m			0.49	*1.02	0.31	*0.72	0.23	*0.61	4.75
	Ground			0.46	*1.19	0.30	*0.78	0.25	*0.62	4.53
	– 1 m	0.89	*1.74	0.46	*1.10			0.31	*0.60	3.91

Notes: 1. Rating are based on SAE J1097.

- 2. Lifting capacity of the ZAXIS Series does not exceed 75% of tipping load with the machine on firm, level ground or 87% full hydraulic capacity.
- 3. The load point is a hook (not standard equipment) located on the back of the bucket.
- 4. \*Load limited by hydraulic capacity



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The Specifications include data that are not applicable to certain areas. Optional equipment may vary with territory specifications. Specifications are subject to change without notice.

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