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The Specifications include data that are not applicable to certain areas. Optional equipment may vary with territory specifications. Specifications are subject to change without notice. KS-E414P Printed in Japan 03.03 (TP/TP, MT<sub>3</sub>)

# **HITACHI**

# **Mini-Excavator** ZAXIS27U Specifications

Rated Engine Power

DIN 6271, net 22.5 kW (30.6 PS)

SAE J1349, net 23.0 kW (30.9 hp) Operating Weight

(Rubber shoes) (Grouser shoes) 2-Pillar canopy version 2 780 kg 2 850 kg 4-Pillar canopy version 2 840 kg 2 910 kg

2 900 kg

2 970 kg

Unit: mm

Unit: mm

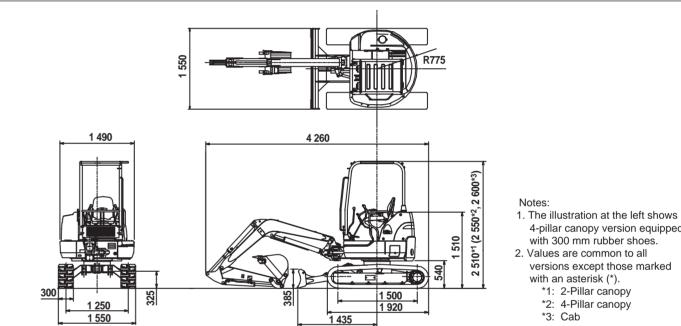
Cab version Backhoe Buckets

 $0.04 - 0.10 \text{ m}^3$ ISO 7451

The 2- or 4-pillar canopy, or cab can be mounted on the upperstructure according to job needs and applicable regulations. The 4-pillar canopy and cab conform to TOPS (ISO 12117) and FOPS (ISO 10262, Level 1)\* requirements.

\* Cab requires optional top guard.

### **■ DIMENSIONS**

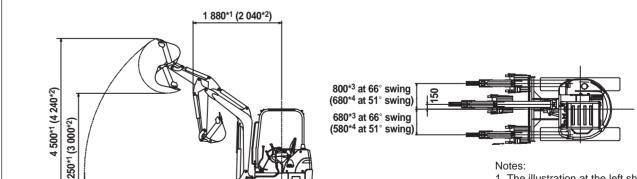


4-pillar canopy version equipped

### **■ WORKING RANGES**

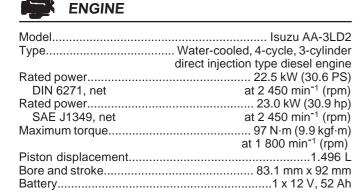
2 650

4 700



- 1. The illustration at the left shows 4-pillar canopy version equipped with 0.08 m<sup>3</sup> bucket, 1.17 m arm and 300 mm rubber shoes.
- 2. Values are common to all versions except those marked with an asterisk (\*).
  - \*1: 2-Pillar canopy
  - \*2: 4-Pillar canopy and cab
  - \*3: 2- and 4-Pillar canopy
  - \*4: Cab







### **HYDRAULIC SYSTEM**

The Optimum Hyraulic System (OHS) uses three pumps for job efficiency and smooth combined operations.

Main pumps	Two variable displacement axial piston pumps
Maximum oil flow	
	One gear pump
Maximum oil flow	
Pilot pump	One gear pump
Maximum oil flow	12.5 L/min

### Relief Valve Settings

Implement circuit	20.6 MPa (210 kgf/cm <sup>2</sup> )
Swing circuit	20.6 MPa (210 kgf/cm²)
Travel circuit	20.6 MPa (210 kgf/cm²)
Pilot circuit	

### **Hydraulic Cylinders**

High-strength piston rods and tubes. Cylinder cushion mechanisms provided in boom raise, arm roll-in and roll-out circuits to absorb shocks at stroke ends.

### **Dimensions**

nm)

No Done Dod die Chalce

Note: The figure in ( ) shows the stroke for 4-pillar canopy version and cab version.



### **CONTROLS**

Hydraulic pilot control levers for all operations.



### **SWING MECHANISM**

High-torque, axial piston motor with planetary reduction gear. Swing circle is single-row, shear-type ball bearing with induction-hardened internal gear. Internal gear and pinion are immersed in lubricant. Swing parking brake is springset/hydraulic-released disc type. Swing shockless valve built in swing motor absorbs shocks when stopping swing, ensuring smooth stops.

Swing speed	. 9.0 min <sup>-1</sup>	(9.0)	rpm	)
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### **UNDERCARRIAGE**

### **Tracks**

Tractor-type undercarriage. Welded track frame using carefully selected materials. Side frame welded to track frame.

Numbers of Rollers on Each Side
Upper roller
Lower rollers

### **Traction Device**

Each track driven by a high-torque, 2-speed axial piston motor through planetary reduction gear, allowing counter-rotation of the tracks. Travel shockless relief valve built in travel motor absorbs shocks when stopping travel, ensuring smooth stops.

Travel speeds (rubber shoes) High: 0 - 4.0 km/h
Low : $0 - 2.4 \text{ km/h}$
Travel speeds (grouser shoes) High: 0 – 3.9 km/h
Low : $0 - 2.3 \text{ km/h}$
Gradeability30 degrees (58%) continuous



### **WEIGHTS AND GROUND PRESSURE**

Equipped with 1.17 m arm and 0.08 m<sup>3</sup> (PCSA heaped) bucket

	Operating weight	Ground pressure
2-Pillar canopy version	_	
300 mm rubber shoes	. 2 780 kg	26 kPa (0.27 kgf/cm <sup>2</sup> )
300 mm grouser shoes	. 2 850 kg	27 kPa (0.28 kgf/cm <sup>2</sup> )
4-Pillar cab version	_	
300 mm rubber shoes	. 2 840 kg	26 kPa (0.27 kgf/cm <sup>2</sup> )
300 mm grouser shoes	. 2 910 kg	27 kPa (0.28 kgf/cm <sup>2</sup> )
Cab version		
300 mm rubber shoes		28 kPa (0.29 kgf/cm <sup>2</sup> )
300 mm grouser shoes.	. 2 970 kg	28 kPa (0.29 kgf/cm <sup>2</sup> )



### FRONT-END ATTACHMENTS

### Backhoe Buckets

7451     Without side cutters     With side cutters     No. of teeth     Weight     1.17 m Std. arm Long am       0.04 m³     250 mm     300 mm     2     46 kg     A     A       0.05 m³     300 mm     350 mm     3 50 kg     A     A       0.06 m³     350 mm     400 mm     3 52 kg     A     A       0.07 m³     400 mm     450 mm     3 55 kg     A     A       0.08 m³     450 mm     500 mm     3 57 kg     A     B
0.05 m³ 300 mm 350 mm 3 50 kg A A   0.06 m³ 350 mm 400 mm 3 52 kg A A   0.07 m³ 400 mm 450 mm 3 55 kg A A
0.06 m <sup>3</sup> 350 mm 400 mm 3 52 kg A A 0.07 m <sup>3</sup> 400 mm 450 mm 3 55 kg A A
0.07 m <sup>3</sup> 400 mm 450 mm 3 55 kg A A
0.09 m <sup>3</sup> 450 mm 500 mm 2 57 kg A B
0.08 III 430 IIIII 300 IIIII 3 37 Kg A B
0.09 m <sup>3</sup>   500 mm   550 mm   4   63 kg   B   B
0.10 m <sup>3</sup>   550 mm   600 mm   4   66 kg   B   C
Arm crowd force   14.8 kN   12.9 kN   (1 510 kgf)   (1 320 kgf)
Bucket digging force 22.6 kN (2 300 kg

A: General digging B: Light-duty digging

C: Loading

### Boom swing angle

2- and 4-pillar canopy versions	Left 66°, Right 66°
Cab version	Left 51°, Right 51°



Zaxis27U

STANDARD EQUIPMENT

• Water-separator for engine fuel system

### **Hydraulic System**

- Hydraulic pilot type control levers
- Pilot control shut-off levers
- Anti-drift valve for front attachments
- Two-speed travel system
- Swing parking brake

### Canopy (Cab)

- Two work lights
- Heater\*\*

**Engine** 

- Windshield wiper\*\*
  - Note: \*: For 4-pillar canopy and cab versions
- Evacuation hammer\*\*
- \*\*: For cab versions Seat belt\*

### Undercarriage

- 300 mm rubber shoes
- Semi-long stay blade

### **Front Attachments**

- 2.1 m boom
- 1.17 m arm
- 0.08 m3 hoe bucket
- Bucket clearance adjusting device
- O-ring type pin-seals for hoe bucket
- HN bushing

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### **OPTIONAL EQUIPMENT**

### Engine

Auto-idling system

### **Hydraulic System**

- Hydraulic P.T.O. port
- Hydraulic piping for breaker
- Travel parking brake
- Swing motion alarm device with lamp
- Travel motion alarm device

### Canopy (Cab)

- Heater\*
- Air cooler\*\*\*
- Seat belt\*
- Windshield washer\*\*\* Notes: \*: For 2-pillar canopy version
- \*\*: For 2- and 4-pillar canopy Wrist rest
- 12V outlet versions
- \*\*\*: For cab version
- Air cleaner inner element
- FOPS top guard\*\*\* • 2-way control lever pattern selector valve

### Undercarriage

- 300 mm grouser shoes
- 400 mm triangle shoes
- 400 mm grouser shoes
- 300 mm pad crawler shoes

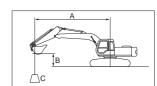
### **Front Attachments**

- 1.47 m arm
- Backhoe buckets; see page 2.

(Excavator/Backhoe loader)

### Counterweight

• Weight-added counterweight (270 kg added)



A: Load radius B: Load point height C: Lifting capacity

### With dozer blade above ground

**■ LIFTING CAPACITIES** 

(Equpipped with 2-pillar canopy)

Rating over-side or 360 degrees Rating over-front

TTICH GOLOI DIGGO G										Offic. 1 000 kg	
		Load Radius							Maximum Reach		
Conditions	Load Point	2 m		3 m		4 m		waxiiiuiii Reach			
	Height		ů		L <sup>1</sup>		<b>L</b>		L L	meter	
	3 m			*0.48	*0.48			0.31	0.33	3.96	
Arm: 1.17 m Bucket: 0.08 m <sup>3</sup>	2 m			0.48	0.53	0.40	0.32	0.24	0.27	4.42	
ISO 7451	1 m			0.45	0.49	0.39	0.31	0.23	0.25	4.52	
Rubber shoes: 300 mm	Ground			0.42	0.46	0.38	0.30	0.25	0.27	4.23	
	– 1 m	0.80	0.90	0.42	0.46			0.32	0.35	3.64	

### With dozer blade on ground

		Load Radius							Marrimum Basah		
Conditions	Load Point	2 m		3 m		4 m		Maximum Reach			
	Height		Ü		Ū		Ū		Ū	meter	
	3 m			*0.48	*0.48			0.31	*0.50	3.96	
Arm: 1.17 m Bucket: 0.08 m <sup>3</sup> ISO 7451 Rubber shoes: 300 mm	2 m			0.48	*0.55	0.40	*0.55	0.24	*0.49	4.42	
	1 m			0.45	*0.81	0.39	*0.60	0.23	*0.53	4.52	
	Ground			0.42	*0.99	0.38	*0.65	0.25	*0.57	4.23	
	– 1 m	0.80	*1.60	0.42	*0.95			0.32	*0.57	3.64	

- Notes: 1. Rating are based on ISO 10567.
  - 2. Lifting capacity does not exceed 75% of tipping load with the machine on firm, level ground or 87% full hydraulic capacity.
- 3. The load point is a hook (not standard equipment) located on the back of the bucket. 4. An asterisk mark (\*) indicates load limited by hydraulic